

UNIVERSITY OF CAMBRIDGE INTERNATIONAL EXAMINATIONS International General Certificate of Secondary Education

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CANDIDATE NAME					
CENTRE NUMBER			CANDIDATE NUMBER		

DESIGN AND TECHNOLOGY

0445/04

Paper 4 Systems and Control

October/November 2007

1 hour

Candidates answer on the Question Paper.

No Additional Materials are required.

To be taken together with Paper 1 in one session of 2 hours 15 minutes.

READ THESE INSTRUCTIONS FIRST

Write your Centre number, candidate number and name on all the work you hand in.

Write in dark blue or black pen.

You may use a soft pencil for any diagrams or graphs.

Do not use staples, paper clips, highlighters, glue or correction fluid.

DO NOT WRITE IN ANY BARCODES.

Section A

Answer all questions.

Section B

Answer one question.

You may use a calculator.

At the end of the examination, fasten all your work securely together.

The number of marks is given in brackets [] at the end of each question or part question.

For Exam	iner's Use
Section A	
Section B	
Total	

This document consists of 14 printed pages and 2 blank pages.

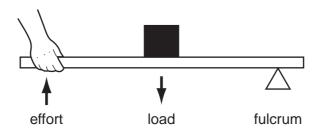


Section A

			tion.	
		2	Ž	2
		Section A		aCan
	A	nswer all questions in this sec	tion.	13
1	Complete the statement below	:		·
	A tie is a structural member ex	xperiencing	force.	[1]
2	Identify the electrical compone	nt shown below.		
	The component shown is	symbol component		[2]
		1		
3	Give one use of this compone Complete the table below.			[1]
	Name	Diagram	Use	
	Pear cam and flat follower		Valve operation	

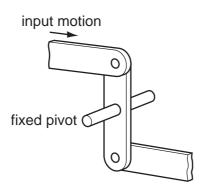
Bicycle transmission

4 Identify the class (order) of lever shown below:



The lever shown is	[1]
Give an example of the use of this class of lever.	
	[1]

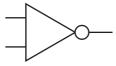
5 The diagram below shows a linkage.



(a)	Add labels to show the direction of the output motion.	[2]
(b)	Name the type of motion shown in the diagram of the linkage above.	
		[1]
(c)	Explain the function of this linkage.	
		[2]

Complete the table below.	4	Use Name Dana Co.	For Examiner's Use
Name	Diagram	Use	50
Honeycomb cells		[1]	COM
[1]		[1]	
'I' Section beam	[2]	Steel framed buildings	

Identify the logic gate shown in the diagram below. 7



		[1]
8	(a) State the purpose of an LDR transducer.	[1]
	(b) Give one example of the use of an LDR.	[1]
9	Give one example of the use of a strain gauge.	[1]
10	Name two methods of reinforcing a square framed structure.	[2]

11 Fig.1 shows a hand drill.

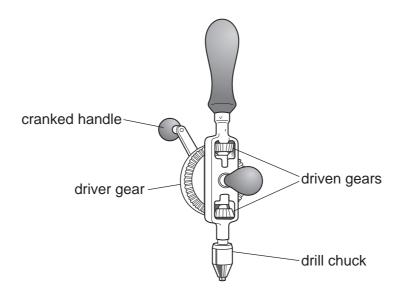


Fig. 1

(a)	Des	scribe the motion conversion that takes place when using a hand drill.	
			[2]
(b)	(i)	Name the type of gear mechanism used in the hand drill shown.	
			[1]
	(ii)	Explain why the driver gear wheel is very much larger than the driven gear wheel	ls.
			•••••
			[2]

		the transfer of the transfer o	
		Give one reason for the top driven gear wheel nearest the handle.	1
	(iii)	Give one reason for the top driven gear wheel nearest the handle.	Can
			[2]
(c)	Exp	plain why the handle is cranked.	
			••••
	•••••		[3]
(d)	The	e driver wheel has 60 teeth and the driven wheels have 12 teeth each.	
	(i)	Calculate the gear ratio for this mechanism.	
			[3]
	(ii)	If the driver wheel is turned at 60 rpm, calculate the speed of the drill chuck.	

(e) Fig. 2 shows a toothed belt drive arrangement.

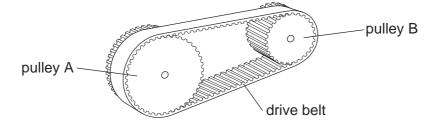


Fig. 2

	(1)	Give one benefit of using this type of belt drive.	
			 [1]
	(ii)	Explain one drawback of using this type of belt drive.	٠,
			 [2]
	(iii)	Give one example of the use of this type of belt drive.	•
			[1]
	(iv)	Explain how you would calculate the Velocity Ratio of this belt drive.	
			•••
			[3]
(f)	Giv	re one other type of pulley drive belt and give one use.	
		[2]

12 Fig.3 shows a variety of both natural and man made structures.

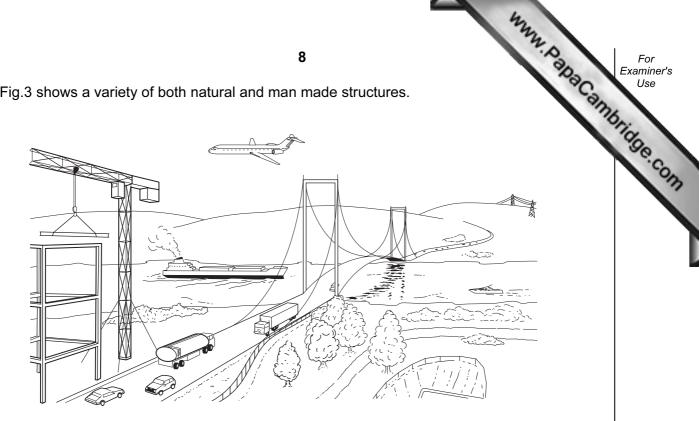


Fig. 3

(a)	(1)	Name one frame structure in Fig.3.	
			[1]
	(ii)	Name one man made shell structure in Fig.3.	
			[1]
(b)	Exp	plain the difference in the way in which frame and shell structures work.	
			[2]

	4
	The state of the s
	9
(c)	Explain the following functions of a structure. Support: [2]
	Support:
	[2]
	Span:
	[2]
	Contain:
	[2]
(d)	Structures can be subjected to static and dynamic forces.
	Explain, using examples, the difference between static and dynamic forces.
	Explain, using examples, the difference between static and dynamic forces.
	[3]

(e) Fig. 4 shows a structure for a roof truss.

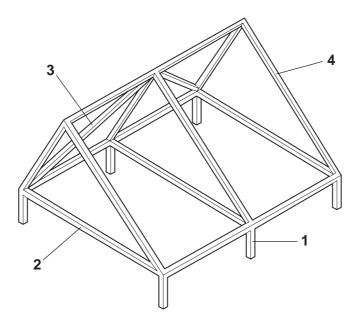


Fig. 4

(i) Name the parts numbered 1 to 3.

1	[1]
2	[1]
3	[1]

(ii) Part 4 is a strut.

Use sketches and notes to explain the type of load experienced by a strut.

(iii) Use sketches and notes to explain why the roof truss is made up of triangles

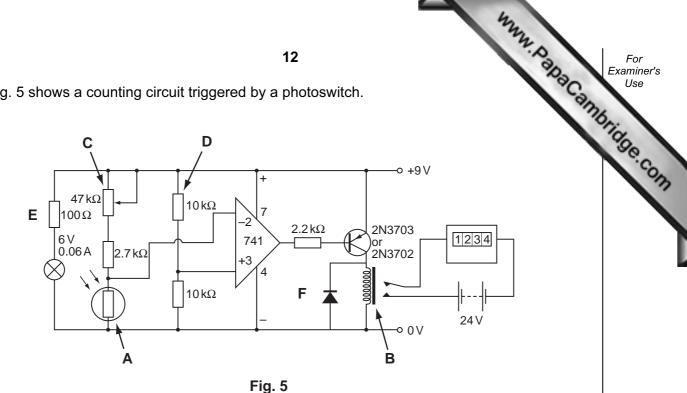
[2]

(iv) Draw one method of reinforcing the joints in the roof truss.

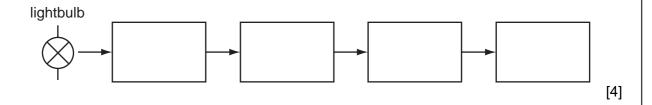
[2]

(f) Use notes and sketches to explain the term redundant member.

13 Fig. 5 shows a counting circuit triggered by a photoswitch.



(a) Complete the block diagram to explain how this counting circuit works each time the light beam, shining on component A, is broken.



(b) (i) Name component B.	
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	[1
--	----

(ii) Explain the purpose of component **B** in this circuit.

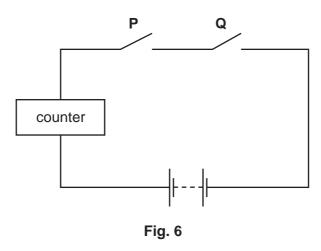
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(iii) Explain the need for component F.

	[2]

	(iv)	Explain the purpose of component C .	Annohidde com
			Tide
			COM
			[3]
	(v)	State the purpose of the resistor E .	
			[1]
(c)	The	e pair of 10 k Ω resistors labelled D are known as a potential divider.	
	Exp	plain the term potential divider.	
		[3]
(d)		plain how the circuit shown in Fig. 5 could be simply modified to count when the lig	ht
			[3]

www.PapaCambridge.com (e) Logic gates could be used to control a counter. Fig. 6 shows a pressure pad circ is used to trigger a counter when a person steps on pad P and, at the same presses the push button Q.



(i) Complete the truth table below for this logic circuit.

Pad P On/Off	Pad Q On/Off	Counter state On/Off
Off	Off	Off
Off	On	
On	Off	
		On

(ii) Identify the type of logic circuit shown. [1] **BLANK PAGE**

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